

DISPLAY Elektronik GmbH

DATA SHEET

TFT MODULE

DEM 320240B MMH-PW-N

5,7" MONO - TFT

Product Specification

Version: 3

11.08.2016

Revision History

| VERSION | DATE | Note |
|----------------|-------------|--------------------------------|
| 0 | 14.10.2015 | First Issue |
| 1 | 04.11.2015 | Modify Initial Code |
| 2 | 21.01.2016 | Modify Static Electricity Test |
| 3 | 11.08.2016 | Modify Vibration Test |

Contents

1. Summary
2. General Specification
3. Interface
4. Counter Drawing
5. Block Diagram
6. Absolute Maximum Ratings
7. Electrical Characteristics
8. DC Characteristics
9. AC Characteristics
10. Optical Characteristics
11. Reliability
12. Initial Code for Reference

1. Summary

This technical specification applies to 5.7' Mono TFT-LCD panel. The 5.7' Mono TFT-LCD panel is designed for camcorder, digital camera application and other electronic products which require high quality flat panel displays. This module follows RoHS.

2. General Specifications

- Size: 5.7 Inch
- Dot Matrix: 320 x 240 dots
- Module Dimension: 160.00 x 109.00 x 7.00 mm
- Active area: 115.20 x 86.40 mm
- Dot pitch: 0.36 x 0.36 mm
- LCD type: MONO TFT, Positive, Transmissive
- View Direction: 12 o'clock
- Gray Scale Inversion Direction: 6 o'clock
- Gray Scale: 16 Gray scale (4BPP)/ 4 Gray scale (2BPP)/ 2 Gray scale (1BPP)
- Driver IC: ST7511U (Sitronix)
- Backlight Type: LED, Normally White
- With / Without TP: Without TP
- Surface: Glare

* Mono tone slight changed by temperature and driving voltage.

3. Interface

3.1. LCM PIN Definition

| Pin | Symbol | Function | Remark |
|-----|--------------|----------------------|--------|
| 1 | GND | System ground | |
| 2 | VDD | Power Supply : +3.3V | |
| 3 | NC | No connect | |
| 4 | A0 | Data/Command select | |
| 5 | /WR(R/W) | Write strobe signal | |
| 6 | /RD(E) | Read strobe signal | |
| 7 | DB0 | Data bus | |
| 8 | DB1 | Data bus | |
| 9 | DB2 | Data bus | |
| 10 | DB3 | Data bus | |
| 11 | DB4 | Data bus | |
| 12 | DB5 | Data bus | |
| 13 | DB6 | Data bus | |
| 14 | DB7 | Data bus | |
| 15 | /CS | Chip select | |
| 16 | /RESET(RSTB) | Hardware reset | |
| 17 | IF0 | Mode select | Note1 |
| 18 | IF1 | | |
| 19 | NC | No connect | |
| 20 | NC | No connect | |
| 21 | NC | No connect | |
| 22 | NC | No connect | |

Note1:

| Setting | | MCU Type | Interface Pin Function | | | | |
|---------|-----|--------------------------|------------------------|----|-----|-----|-------------------------------------|
| IF1 | IF0 | | CSB | A0 | RWR | ERD | D[7:0] |
| L | L | Parallel 8080 series MCU | CSB | A0 | /WR | /RD | D[7:0] |
| L | H | Parallel 6800 series MCU | | | R/W | E | D[7:0] |
| H | H | Serial 4-Line series MCU | | | - | - | D7=SCL, D0=SDA, D[6:1] are not used |
| H | L | Serial 3-Line series MCU | | | - | - | |

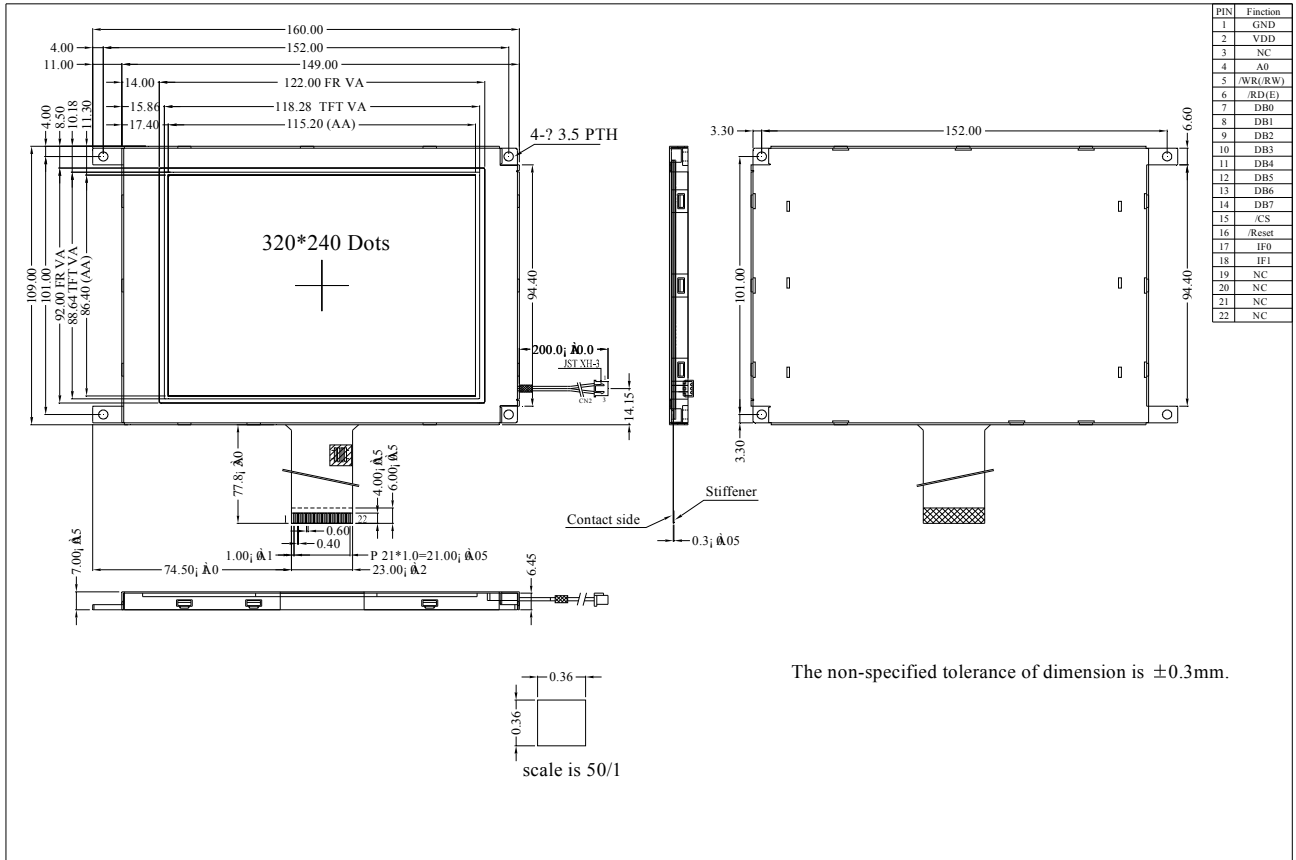
The un-used pins are marked as “-” and should be connected to “H” by VDDI.

3.2. Backlight Unit Section (CN2)

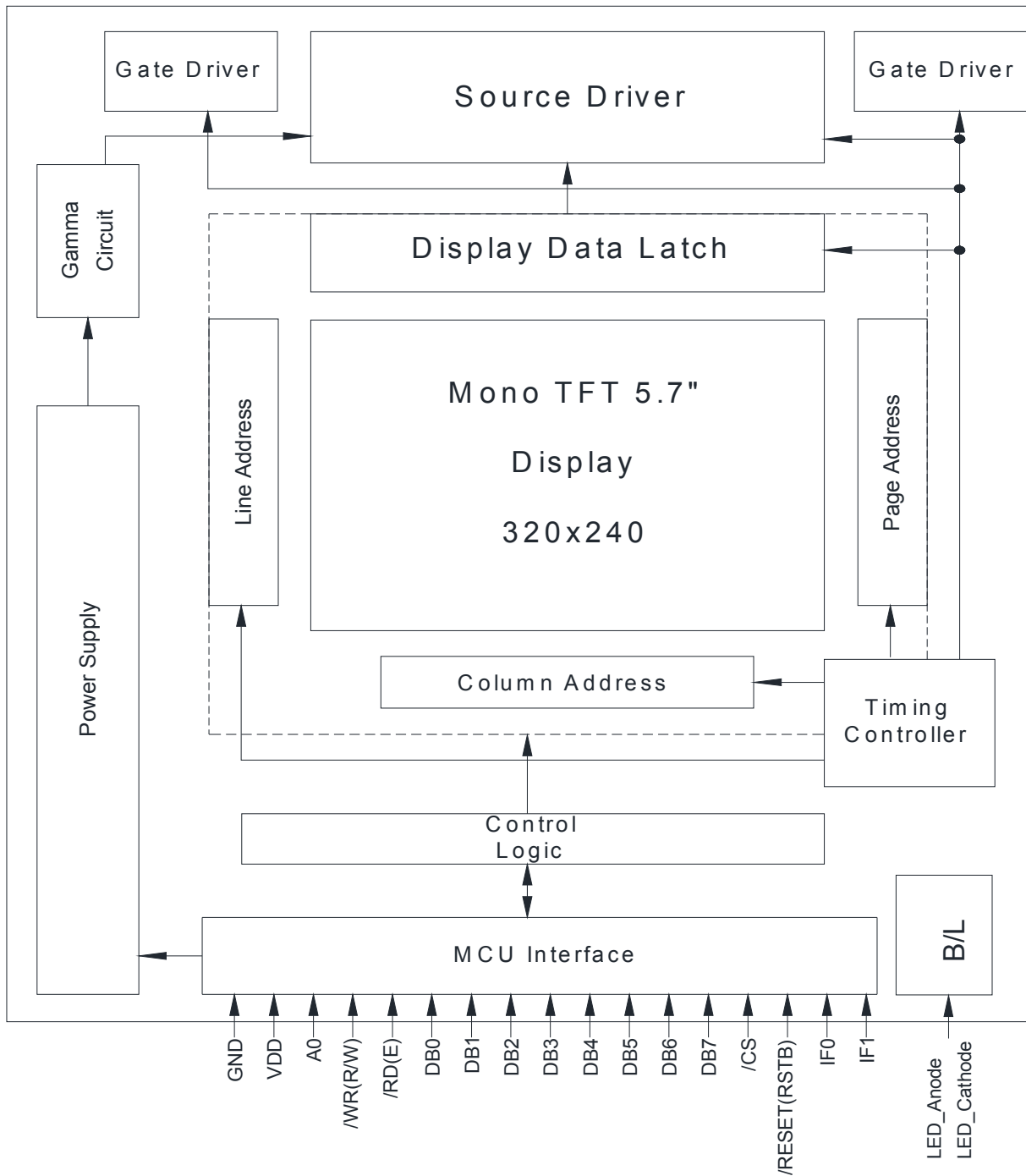
LED Light Bar connector is used for the the integral backlight system. The recommended model is “JST XH-3” manufactured by JST.

| Pin No. | Symbol | I/O | Function | Remark |
|---------|-------------------|-----|-------------------------------------|--------|
| 1 | V _{LED+} | P | Power for LED backlight anode (A) | Red |
| 3 | V _{LED-} | P | Power for LED backlight cathode (K) | White |

4. Counter Drawing



5. Block Diagram

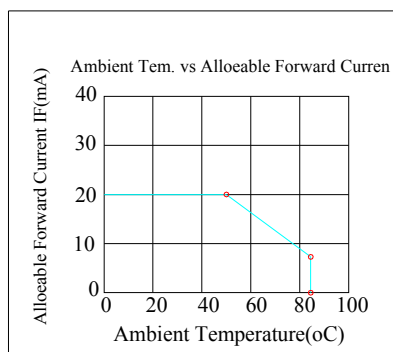


6. Absolute Maximum Ratings

| Item | Symbol | Min | Typ | Max | Unit |
|-----------------------|-----------------|-----|-----|-----|------|
| Operating Temperature | T _{OP} | -20 | — | +70 | °C |
| Storage Temperature | T _{ST} | -30 | — | +80 | °C |

Note: Device is subject to be damaged permanently if stresses beyond those absolute maximum ratings listed above

- Temp. $\leq 60^{\circ}\text{C}$, 90% RH MAX. Temp. $> 60^{\circ}\text{C}$, Absolute humidity shall be less than 90% RH at 60°C



7. Electrical Characteristics

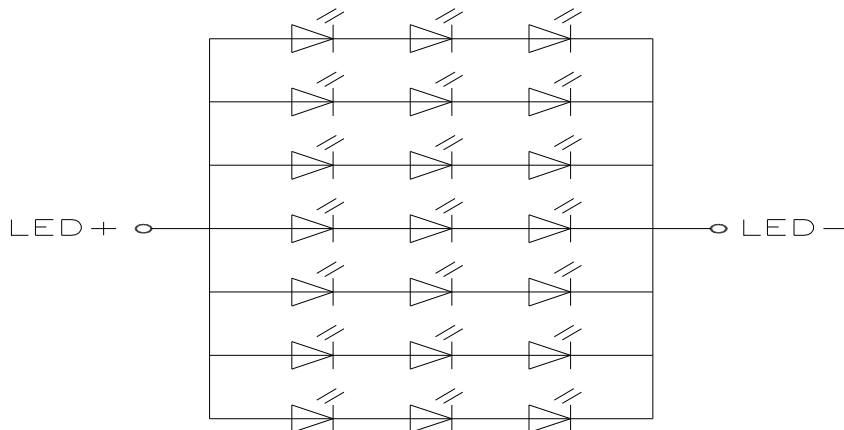
7.1. Operating conditions:

| Item | Symbol | Condition | Min | Typ | Max | Unit | Remark |
|------------------------|--------|-----------|-----|-----|-----|------|--------|
| Supply Voltage For LCM | VDD | — | 3.0 | 3.3 | 3.6 | V | |
| Supply Current For LCM | IDD | — | — | 20 | 30 | mA | Note1 |
| Power Consumption | — | — | — | 66 | 108 | mW | |

Note1: This value is test for VDD=3.3V only

7.2. LED driving conditions

| Parameter | Symbol | Min. | Typ. | Max. | Unit | Remark |
|-------------------|--------|------|--------|------|------|------------|
| LED Current | | - | 140 | - | mA | |
| Power Consumption | | 1120 | - | 1386 | mW | |
| LED Voltage | VLED+ | 8.0 | 9.0 | 9.9 | V | Note 1 |
| LED Lifetime | | - | 50,000 | - | Hr | Note 2,3,4 |



Note 1: Power supply the back light specification

Note 2: Ta = 25°C

Note 3: Brightness to be decreased to 50% of the initial value

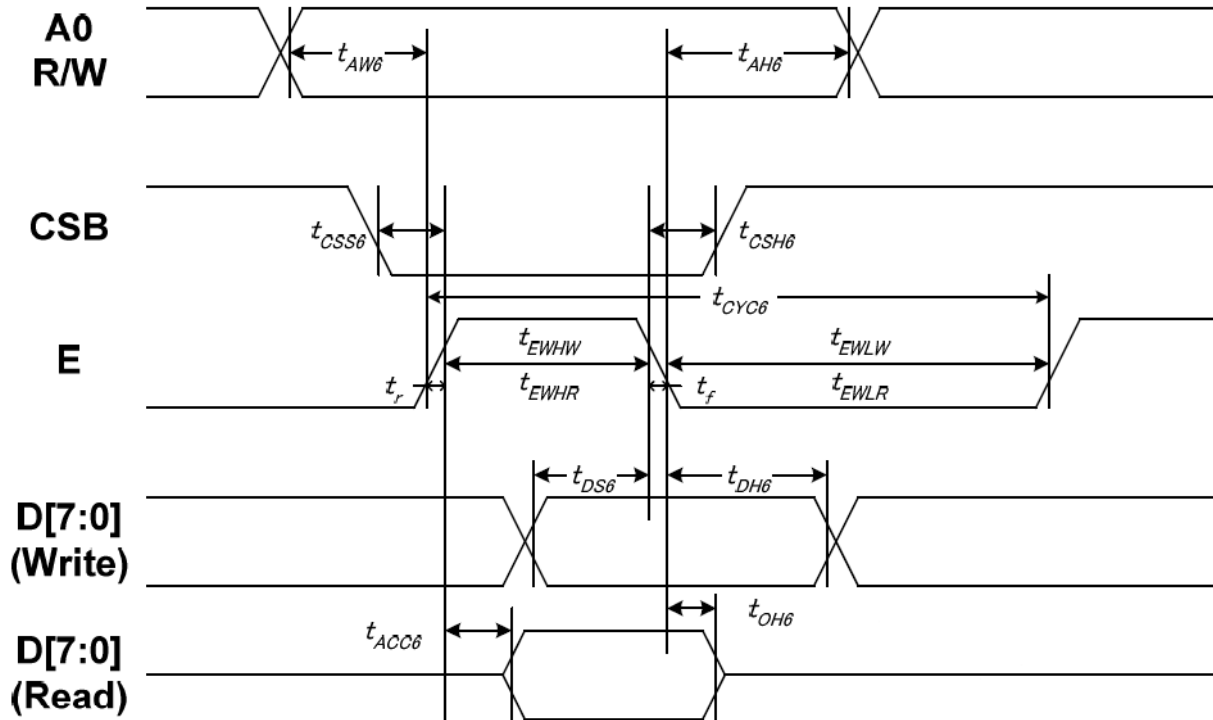
Note 4: The single LED lamp case

8. DC CHARATERISTICS

| Parameter | Symbol | Rating | | | Unit | Condition |
|--------------------------|-----------------|--------|-----|--------|------|-----------|
| | | Min | Typ | Max | | |
| Low Level Input Voltage | V _{IL} | 0 | - | 0.3VDD | V | |
| High Level Input Voltage | V _{IH} | 0.7VDD | - | VDD | V | |

9. AC Characteristics

9.1. System Bus Timing for 6800 Series MPU

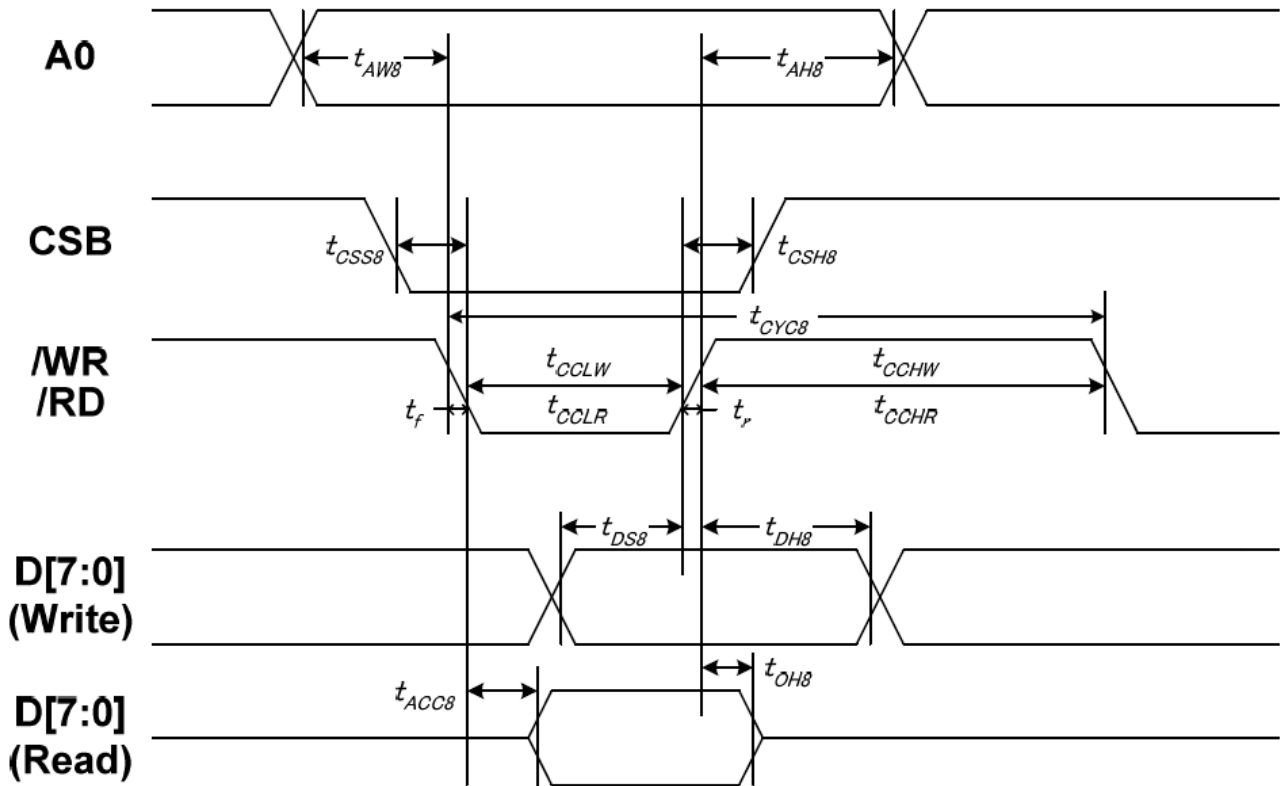


| Item | Signal | Symbol | Condition | Min | Max | Unit |
|-------------------------------|--------|--------|-------------|-----|-----|------|
| Address setup time | A0 | tAW6 | - | 10 | - | ns |
| Address hold time | | tAH6 | - | 0 | - | |
| System cycle time | E | tCYC6 | - | 200 | - | |
| Enable L pulse width (WRITE) | | tEHLW | - | 100 | - | |
| Enable H pulse width (WRITE) | | tEHLR | - | 100 | - | |
| Enable L pulse width (READ) | | tEHLR | - | 130 | - | |
| Enable H pulse width (READ) | | tEHLR | - | 130 | - | |
| CSB setup time | | CSB | tCSS6 | - | 100 | |
| CSB hold time | tCSH6 | | - | 100 | - | |
| Write data setup time | D[7:0] | tDS6 | - | 70 | - | |
| Write data hold time | | tDH6 | - | 20 | - | |
| Read data access time | | tACC6 | CL = 100 pF | - | 80 | |
| Read data output disable time | | tOH6 | CL = 100 pF | 15 | 80 | |

Note:

- The input signal rise time and fall time (t_r , t_f) is specified at 15 ns or less.
When the system cycle time is extremely fast,
 $(t_r + t_f) \leq (t_{CYC6} - t_{CCLW} - t_{CCHW})$ for $(t_r + t_f) \leq (t_{CYC6} - t_{CCLR} - t_{CCHR})$ are specified.
- All timing is specified using 20% and 80% of VDDI as the reference.
- t_{CCLW} and t_{CCLR} are specified as the overlap between CSB being "L" and /WR and /RD being at the "L" level. CSB and /WR (or /RD) cannot act at the same time and CSB should be 100ns wider than /WR (or /RD).

10.2. System Bus Timing for 8080 Series MPU

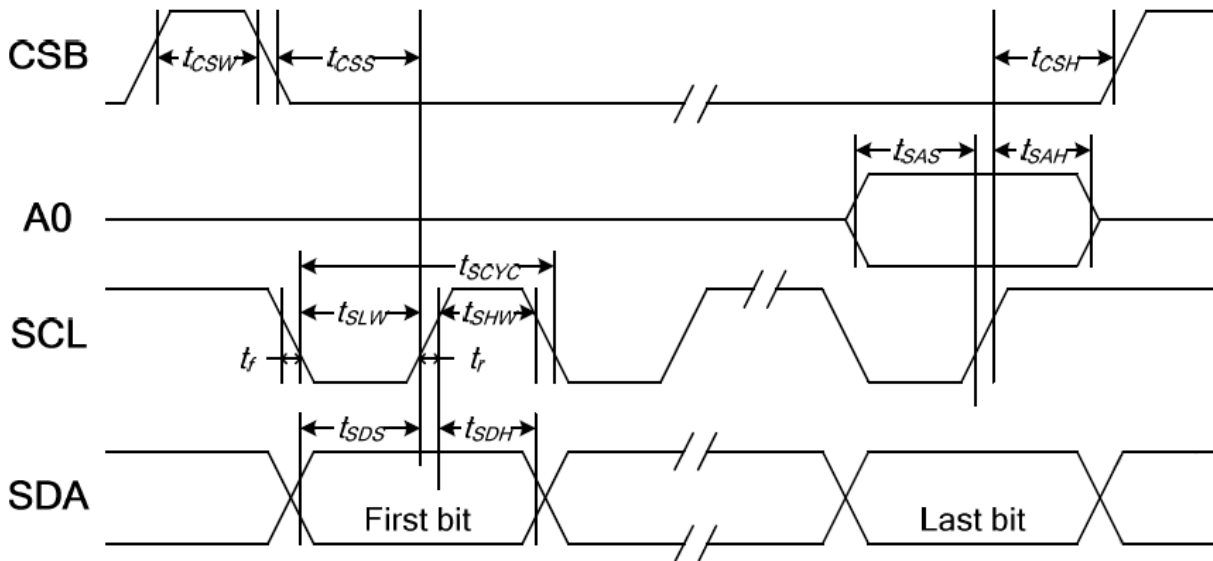


| Item | Signal | Symbol | Condition | Min | Max | Unit |
|-------------------------------|------------|------------|-------------|-----|-----|------|
| Address setup time | A0 | t_{AW8} | - | 10 | - | ns |
| Address hold time | | t_{AH8} | - | 0 | - | |
| System cycle time | /WR | t_{CYC8} | - | 200 | - | |
| /WR L pulse width (WRITE) | | t_{CCLW} | - | 100 | - | |
| /WR H pulse width (WRITE) | | t_{CCHW} | - | 100 | - | |
| /RD L pulse width (READ) | | /RD | t_{CCLR} | - | 120 | |
| /RD H pulse width (READ) | t_{CCHR} | | - | 120 | - | |
| CSB setup time | CSB | t_{CSS8} | - | 100 | - | |
| CSB hold time | | t_{CSH8} | - | 100 | - | |
| Write data setup time | D[7:0] | t_{DS8} | - | 70 | - | |
| Write data hold time | | t_{DH8} | - | 20 | - | |
| Read data access time | | t_{ACC8} | CL = 100 pF | - | 80 | |
| Read data output disable time | | t_{OH8} | CL = 100 pF | 15 | 80 | |

Note:

- The input signal rise time and fall time (t_r , t_f) is specified at 15 ns or less.
When the system cycle time is extremely fast,
 $(t_r + t_f) \leq (t_{CYC8} - t_{CCLW} - t_{CCHW})$ for $(t_r + t_f) \leq (t_{CYC8} - t_{CCLR} - t_{CCHR})$ are specified.
- All timing is specified using 20% and 80% of VDDI as the reference.
- t_{CCLW} and t_{CCLR} are specified as the overlap between CSB being "L" and /WR and /RD being at the "L" level. CSB and /WR (or /RD) cannot act at the same time and CSB should be 100ns wider than /WR (or /RD).

10.3. System Bus Timing for 4-Line Serial Interface

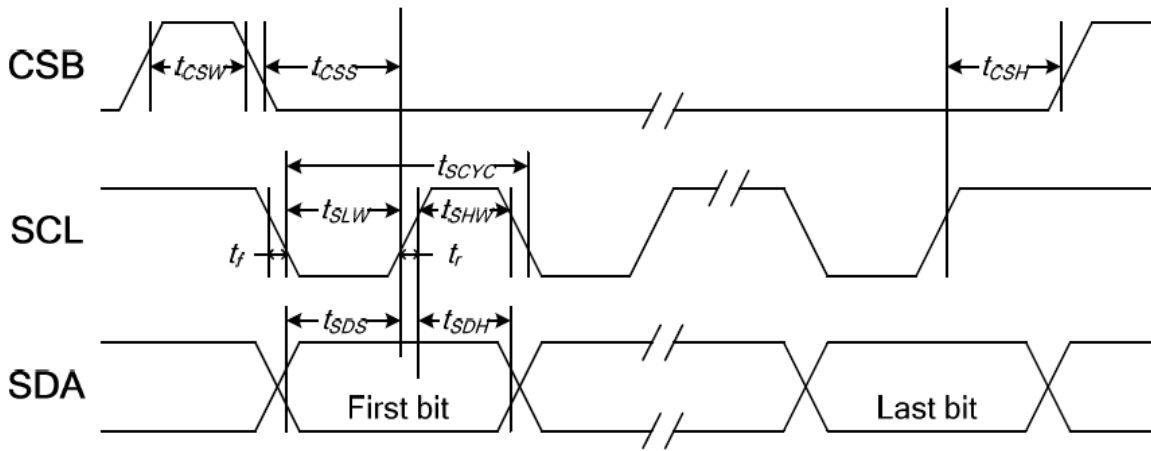


| Item | Signal | Symbol | Condition | Min | Max | Unit |
|---------------------|--------|--------|-----------|-----|-----|------|
| Serial clock period | | tSCYC | - | 80 | - | ns |
| SCL "H" pulse width | SCL | tSHW | - | 40 | - | |
| SCL "L" pulse width | SCL | tSLW | - | 40 | - | |
| Address setup time | A0 | tSAS | - | 40 | - | |
| Address hold time | A0 | tSAH | - | 40 | - | |
| Data setup time | SDA | tSDS | - | 15 | - | |
| Data hold time | SDA | tSDH | - | 20 | - | |
| CSB-SCL time | CSB | tCSS | - | 40 | - | |
| CSB-SCL time | CSB | tCSH | - | 40 | - | |
| CSB "H" pulse width | CSB | tCSW | - | 15 | - | |

Note:

1. The input signal rise and fall time (t_r , t_f) are specified at 15 ns or less.
2. All timing is specified using 20% and 80% of VDDI as the standard.

10.4. System Bus Timing for 3-Line Serial Interface



| Item | Signal | Symbol | Condition | Min | Max | Unit |
|---------------------|--------|--------|-----------|-----|-----|------|
| Serial clock period | | tSCYC | - | 80 | - | ns |
| SCL "H" pulse width | SCL | tSHW | - | 40 | - | |
| SCL "L" pulse width | | tSLW | - | 40 | - | |
| Data setup time | SDA | tSDS | - | 15 | - | |
| Data hold time | | tSDH | - | 20 | - | |
| CSB-SCL time | CSB | tCSS | - | 40 | - | |
| CSB-SCL time | | tCSH | - | 40 | - | |
| CSB "H" pulse width | | tCSW | - | 15 | - | |

Note:

1. The input signal rise and fall time (t_r , t_f) are specified at 15 ns or less.
2. All timing is specified using 20% and 80% of VDDI as the standard.

10. Optical Characteristics

| Item | Symbol | Condition. | Min | Typ. | Max. | Unit | Remark |
|---|--------|-----------------------------------|--------------|------|------|-------------------|-------------------|
| Response Time | Tr | $\theta=0^\circ$ 、 $\phi=0^\circ$ | - | 20 | 30 | .ms | Note 3,5 |
| | Tf | | - | 10 | 15 | .ms | |
| Contrast Ratio | CR | At optimized viewing angle | - | 800 | - | - | Note 4,5 |
| Viewing Angle (Gray Scale Inversion Direction) | Hor. | Θ_R | $CR \geq 10$ | 60 | | Deg. | Note 1 |
| | | Θ_L | | 60 | | | |
| | Ver. | Φ_T | | 60 | | | |
| | | Φ_B | | 50 | | | |
| Brightness | - | - | 900 | 1000 | - | Cd/m ² | Center of display |

Ta=25±2°C, IL=140mA

Note 1: Definition of viewing angle range

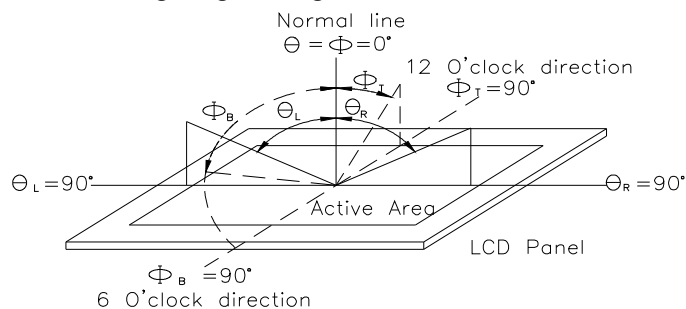


Fig.11.1. Definition of viewing angle

Note 2: Test equipment setup:

After stabilizing and leaving the panel alone at a driven temperature for 10 minutes, the measurement should be executed. Measurement should be executed in a stable, windless, and dark room. Optical specifications are measured by Topcon BM-7orBM-5 luminance meter 1.0° field of view at a distance of 50cm and normal direction.

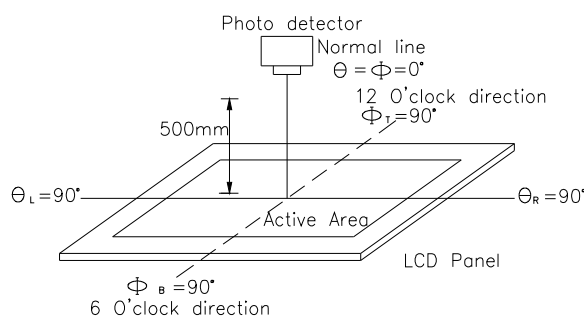
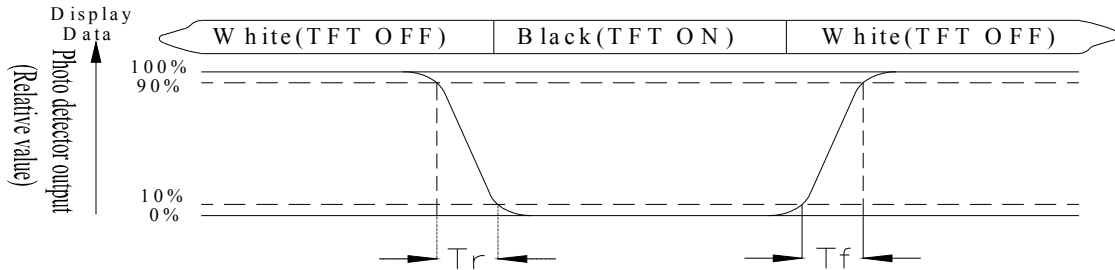


Fig. 11.2. Optical measurement system setup

Note 3: Definition of Response time:

The response time is defined as the LCD optical switching time interval between “White” state and “Black” state. Rise time, T_r , is the time between photo detector output intensity changed from 90% to 10%. And fall time, T_f , is the time between photo detector output intensity changed from 10% to 90%



Note 4: Definition of contrast ratio:

The contrast ratio is defined as the following expression.

$$\text{Contrast ratio (CR)} = \frac{\text{Luminance measured when LCD on the "White" state}}{\text{Luminance measured when LCD on the "Black" state}}$$

Note 5: White $V_i = V_{i50} \pm 1.5V$

Black $V_i = V_{i50} \pm 2.0V$

“±” means that the analog input signal swings in phase with VCOM signal.

“±” means that the analog input signal swings out of phase with VCOM signal.

The 100% transmission is defined as the transmission of LCD panel when all the input terminals of module are electrically opened.

Note 6: Measured at the center area of the panel when all the input terminals of LCD panel are electrically opened.

11. Reliability

Content of Reliability Test (Wide temperature, -20°C~70°C)

| Environmental Test | | | |
|--------------------------------------|--|--|------|
| Test Item | Content of Test | Test Condition | Note |
| High Temperature storage | Endurance test applying the high storage temperature for a long time. | 80°C 200hrs | 2 |
| Low Temperature storage | Endurance test applying the low storage temperature for a long time. | -30°C 200hrs | 1,2 |
| High Temperature Operation | Endurance test applying the electric stress (Voltage & Current) and the thermal stress to the element for a long time. | 70°C 200hrs | — |
| Low Temperature Operation | Endurance test applying the electric stress under low temperature for a long time. | -20°C 200hrs | 1 |
| High Temperature/ Humidity Operation | The module should be allowed to stand at 60□,90%RH max | 60°C,90%RH 96hrs | 1,2 |
| Thermal shock resistance | The sample should be allowed stand the following 10 cycles of operation <div style="text-align: center;"> <p style="margin: 0;">-20°C 25°C 70°C</p> <p style="margin: 0;">30min 5min 30min</p> <p style="margin: 0;">1 cycle</p> </div> | -20°C/70°C 10 cycles | — |
| Vibration test | Endurance test applying the vibration during transportation and using. | Total fixed amplitude : 3 1.5mm Vibration Frequency : 10~55Hz One cycle 60 seconds to 3 directions of X,Y,Z for Each 15 minutes | 3 |
| Static electricity test | Endurance test applying the electric stress to the terminal. | VS=±600V(contact), ±800v(air), RS=330Ω CS=150pF 10 times | — |

Note1: No dew condensation to be observed.

Note2: The function test shall be conducted after 4 hours storage at the normal Temperature and humidity after remove from the test chamber.

Note3: The packing have to including into the vibration testing.

12. Initial Code for Reference

```
void Initial_code()
{
    Write_Command(0xae);
    Write_Data(0xa5);

    Write_Command(0x61);
    Write_Data(0x8f);
    Write_Data(0x04);
    Write_Data(0xa5);
    Write_Data(0xa5);

    Write_Command(0x62);
    Write_Data(0x36);
    Write_Data(0x0b);
    Write_Data(0x0b);
    Write_Data(0xa5);

    Write_Command(0x33);
    Write_Data(0x07);
    Write_Data(0x2c);
    Write_Data(0x09);
    Write_Data(0x2a);

    Write_Command(0x63);
    Write_Data(0x09);
    Write_Data(0x17);
    Write_Data(0xa5);
    Write_Data(0xa5);

    Write_Command(0x91);
    Write_Data(0x00);
    Write_Data(0x16);
    Write_Data(0x1B);
    Write_Data(0x1C);
    Write_Command(0x92);
    Write_Data(0x1E);
    Write_Data(0x1F);
```

Write_Data(0x20);
Write_Data(0x21);
Write_Command(0x93);
Write_Data(0x23);
Write_Data(0x24);
Write_Data(0x26);
Write_Data(0x28);
Write_Command(0x94);
Write_Data(0x2B);
Write_Data(0x2F);
Write_Data(0x34);
Write_Data(0x3f);
Write_Command(0x99);
Write_Data(0x00);
Write_Data(0x16);
Write_Data(0x1B);
Write_Data(0x1C);
Write_Command(0x9a);
Write_Data(0x1E);
Write_Data(0x1F);
Write_Data(0x20);
Write_Data(0x21);
Write_Command(0x9b);
Write_Data(0x23);
Write_Data(0x24);
Write_Data(0x26);
Write_Data(0x28);
Write_Command(0x9c);
Write_Data(0x2B);
Write_Data(0x2F);
Write_Data(0x34);
Write_Data(0x3F);

Write_Command(0x12);
Write_Data(0xa5);

Write_Command(0x24);
Write_Data(0x01);
Write_Data(0xa5);
Write_Data(0xa5);
Write_Data(0xa5);

Write_Command(0x22);

Write_Data(0x00);

Write_Data(0xa5);

Write_Data(0xa5);

Write_Data(0xa5);

Write_Command(0x15);

Write_Data(0xa5);

nop();

}